

## NAG C Library Function Document

### nag\_tsa\_resid\_corr (g13asc)

#### 1 Purpose

nag\_tsa\_resid\_corr (g13asc) is a diagnostic checking routine suitable for use after fitting a Box–Jenkins ARMA model to a univariate time series using nag\_tsa\_multi\_inp\_model\_estim (g13bec). The residual autocorrelation function is returned along with an estimate of its asymptotic standard errors and correlations. Also, nag\_tsa\_resid\_corr calculates the Box–Ljung portmanteau statistic and its significance level for testing model adequacy.

#### 2 Specification

```
#include <nag.h>
#include <nagg13.h>

void nag_tsa_resid_corr (Nag_ArimaOrder *arimav, Integer n, const double v[],
                         Integer m, const double par[], Integer narma, double r[],
                         double rc[], Integer tdrc, double *chi, Integer *df, double *siglev,
                         NagError *fail)
```

#### 3 Description

Consider the univariate multiplicative autoregressive-moving average model

$$\phi(B)\Phi(B^s)(W_t - \mu) = \theta(B)\Theta(B^s)\epsilon_t \quad (1)$$

where  $W_t$ , for  $t = 1, 2, \dots, n$  denotes a time series and  $\epsilon_t$ , for  $t = 1, 2, \dots, n$  is a residual series assumed to be normally distributed with zero mean and variance  $\sigma^2 (> 0)$ . The  $\epsilon_t$ 's are also assumed to be uncorrelated. Here  $\mu$  is the overall mean term,  $s$  is the seasonal period and  $B$  is the backward shift operator such that  $B^r W_t = W_{t-r}$ . The polynomials in (1) are defined as follows:

$$\phi(B) = 1 - \phi_1 B - \phi_2 B^2 - \dots - \phi_p B^p$$

is the non-seasonal autoregressive (AR) operator;

$$\theta(B) = 1 - \theta_1 B - \theta_2 B^2 - \dots - \theta_q B^q$$

is the non-seasonal moving average (MA) operator;

$$\Phi(B^s) = 1 - \Phi_1 B^s - \Phi_2 B^{2s} - \dots - \Phi_P B^{Ps}$$

is the seasonal AR operator; and

$$\Theta(B^s) = 1 - \Theta_1 B^s - \Theta_2 B^{2s} - \dots - \Theta_Q B^{Qs}$$

is the seasonal MA operator. The model (1) is assumed to be stationary, that is the zeros of  $\phi(B)$  and  $\Phi(B^s)$  are assumed to lie outside the unit circle. The model (1) is also assumed to be invertible, that is the zeros of  $\theta(B)$  and  $\Theta(B^s)$  are assumed to lie outside the unit circle. When both  $\Phi(B^s)$  and  $\Theta(B^s)$  are absent from the model, that is when  $P = Q = 0$ , then the model is said to be non-seasonal.

The estimated residual autocorrelation coefficient at lag  $l$ ,  $\hat{r}_l$ , is computed as:

$$\hat{r}_l = \frac{\sum_{t=l+1}^n (\hat{\epsilon}_{t-l} - \bar{\epsilon})(\hat{\epsilon}_t - \bar{\epsilon})}{\sum_{t=1}^n (\hat{\epsilon}_t - \bar{\epsilon})^2}, \quad l = 1, 2, \dots$$

where  $\hat{\epsilon}_t$  denotes an estimate of the  $t$ th residual,  $\epsilon_t$ , and  $\bar{\epsilon} = \sum_{t=1}^n \hat{\epsilon}_t / n$ . A portmanteau statistic,  $Q_{(m)}$ , is calculated from the formula (see Box and Ljung (1978)):

$$Q_{(m)} = n(n+2) \sum_{l=1}^m \hat{r}_l^2 / (n-l)$$

where  $m$  denotes the number of residual autocorrelations computed. (Advice on the choice of  $m$  is given in Section 6.) Under the hypothesis of model adequacy,  $Q_{(m)}$  has an asymptotic  $\chi^2$  distribution on  $m - p - q - P - Q$  degrees of freedom. Let  $\hat{r}^T = (\hat{r}_1, \hat{r}_2, \dots, \hat{r}_m)$  then the variance-covariance matrix of  $\hat{r}$  is given by:

$$\text{Var}(\hat{r}) = [I_m - X(X^T X)^{-1} X^T]/n.$$

The construction of the matrix  $X$  is discussed in McLeod (1978). (Note that the mean,  $\mu$ , and the residual variance,  $\sigma^2$ , play no part in calculating  $\text{Var}(\hat{r})$  and therefore are not required as input to nag\_tsa\_resid\_corr.)

## 4 Parameters

1: **arimav** – Nag\_ArimaOrder \*

Pointer to structure of type **Nag\_ArimaOrder** with the following members:

<b>p</b> – Integer	<i>Input</i>
<b>d</b> – Integer	<i>Input</i>
<b>q</b> – Integer	<i>Input</i>
<b>bigp</b> – Integer	<i>Input</i>
<b>bigd</b> – Integer	<i>Input</i>
<b>bigq</b> – Integer	<i>Input</i>
<b>s</b> – Integer	<i>Input</i>

These seven members of **arimav** must specify the orders vector  $(p, d, q, P, D, Q, s)$ , respectively, of the ARIMA model for the output noise component.

$p$ ,  $q$ ,  $P$  and  $Q$  refer, respectively, to the number of autoregressive ( $\phi$ ), moving average ( $\theta$ ), seasonal autoregressive ( $\Phi$ ) and seasonal moving average ( $\Theta$ ) parameters.

$d$ ,  $D$  and  $s$  refer, respectively, to the order of non-seasonal differencing, the order of seasonal differencing and the seasonal period.

*Constraints:*

$$\begin{aligned} \mathbf{p}, \mathbf{q}, \mathbf{bigp}, \mathbf{bigq}, \mathbf{s} &\geq 0, \\ \mathbf{p} + \mathbf{q} + \mathbf{bigp} + \mathbf{bigq} &> 0, \\ \text{if } \mathbf{s} = 0, \text{ then } \mathbf{bigp} &= 0 \text{ and } \mathbf{bigq} = 0. \end{aligned}$$

2: **n** – Integer *Input*

*On entry:* the number of observations in the residual series,  $n$ .

*Constraint:*  $\mathbf{n} \geq 3$ .

3: **v[n]** – const double *Input*

*On entry:*  $\mathbf{v}(t)$  must contain an estimate of  $\epsilon_t$ , for  $t = 1, 2, \dots, n$ .

*Constraint:*  $\mathbf{v}$  must contain at least two distinct elements.

4: **m** – Integer *Input*

*On entry:* the value of  $m$ , the number of residual autocorrelations to be computed. See Section 6 for advice on the value of  $m$ .

*Constraint:*  $\mathbf{narma} < \mathbf{m} < \mathbf{n}$ .

5: **par[narma]** – const double *Input*

*On entry:* the parameter estimates in the order  $\phi_1, \phi_2, \dots, \phi_p, \theta_1, \theta_2, \dots, \theta_q, \Phi_1, \Phi_2, \dots, \Phi_P, \Theta_1, \Theta_2, \dots, \Theta_Q$  only.

*Constraint:* the elements in **par** must satisfy the stationarity and invertibility conditions.

6:	<b>narma</b> – Integer	<i>Input</i>
	<i>On entry:</i> the number of ARMA parameters, $\phi$ , $\theta$ , $\Phi$ and $\Theta$ parameters, i.e., <b>narma</b> = $p + q + P + Q$ .	
	<i>Constraint:</i> <b>narma</b> = <b>arima.p</b> + <b>arima.q</b> + <b>arima.bigp</b> + <b>arima.bigq</b> .	
7:	<b>r[m]</b> – double	<i>Output</i>
	<i>On exit:</i> an estimate of the residual autocorrelation coefficient at lag $l$ , for $l = 1, 2, \dots, m$ . If <b>fail.code</b> = <b>NE_G13AS_ZERO_VAR</b> on exit then all elements of <b>r</b> are set to zero.	
8:	<b>rc[m][tdrc]</b> – double	<i>Output</i>
	<i>On exit:</i> the estimated standard errors and correlations of the elements in the array <b>r</b> . The correlation between <b>r</b> [ $i - 1$ ] and <b>r</b> [ $j - 1$ ] is returned as <b>rc</b> [ $i - 1$ ][ $j - 1$ ] except that if $i = j$ then <b>rc</b> [ $i - 1$ ][ $j - 1$ ] contains the standard error of <b>r</b> [ $i - 1$ ]. If on exit, <b>fail.code</b> = <b>NE_G13AS_FACT</b> or <b>NE_G13AS_DIAG</b> , then all off-diagonal elements of <b>rc</b> are set to zero and all diagonal elements are set to $1/\sqrt{n}$ .	
9:	<b>tdrc</b> – Integer	<i>Input</i>
	<i>On entry:</i> the second dimension of the array <b>rc</b> as declared in the function from which <b>nag_tsa_resid_corr</b> is called.	
	<i>Constraint:</i> <b>tdrc</b> $\geq m$ .	
10:	<b>chi</b> – double *	<i>Output</i>
	<i>On exit:</i> the value of the portmanteau statistic, $Q_{(m)}$ . If <b>fail.code</b> = <b>NE_G13AS_ZERO_VAR</b> on exit then <b>chi</b> is returned as zero.	
11:	<b>df</b> – Integer *	<i>Output</i>
	<i>On exit:</i> the number of degrees of freedom of <b>chi</b> .	
12:	<b>siglev</b> – double *	<i>Output</i>
	<i>On exit:</i> the significance level of <b>chi</b> based on <b>idf</b> degrees of freedom. If <b>fail.code</b> = <b>NE_G13AS_ZERO_VAR</b> on exit then <b>siglev</b> is returned as one.	
13:	<b>fail</b> – NagError *	<i>Input/Output</i>
	The NAG error parameter (see the Essential Introduction).	

## 5 Error Indicators and Warnings

### NE\_ARIMA\_INPUT

On entry, **arima.p** = <value>, **arima.d** = <value>, **arima.q** = <value>, **arima.bigp** = <value>, **arima.bigd** = <value>, **arima.bigq** = <value> and **arima.s** = <value>.

Constraints on the members of **arima** are:

**p**, **q**, **bigp**, **bigq**, **s**  $\geq 0$ , **p** + **q** + **bigp** + **bigq**  $> 0$ , if **s** = 0, then **bigp** = 0 and **bigq** = 0.

### NE\_INPUT\_NARMA

On entry, **arima.p** = <value>, **arima.q** = <value>, **arima.bigp** = <value>, **arima.bigq** = <value> while **narma** = <value>.

Constraint: **narma** = **arima.p** + **arima.q** + **arima.bigp** + **arima.bigq**.

**NE\_INT\_3**

On entry,  $\mathbf{m} = <\text{value}>$ ,  $\mathbf{n} = <\text{value}>$ ,  $\mathbf{narma} = <\text{value}>$ .  
 Constraint:  $\mathbf{narma} < \mathbf{m} < \mathbf{n}$ .

**NE\_2\_INT\_ARG\_LT**

On entry,  $\mathbf{tdrc} = <\text{value}>$  while  $\mathbf{m} = <\text{value}>$ . These parameters must satisfy  $\mathbf{tdrc} \geq \mathbf{m}$ .

**NE\_INT\_ARG\_LT**

On entry,  $\mathbf{n}$  must not be less than 3:  $\mathbf{n} = <\text{value}>$ .

**NE\_G13AS\_AR**

On entry, the autoregressive (or moving average) parameters are extremely close to or outside the stationarity (or invertibility) region. To proceed, the user must supply different parameter estimates in the array **par**.

**NE\_G13AS\_ZERO\_VAR**

On entry, the residuals are practically identical giving zero (or near zero) variance. In this case **chi** is set to zero, **siglev** to one and all the elements of **r** set to zero.

**NE\_G13AS\_ITER**

This is an unlikely exit brought about by an excessive number of iterations being needed to evaluate the zeros of the AR or MA polynomials. All output parameters are undefined.

**NE\_G13AS\_FACT**

On entry, one or more of the AR operators has a factor in common with one or more of the MA operators. To proceed, this common factor must be deleted from the model. In this case, the off-diagonal elements of **rc** are returned as zero and the diagonal elements set to  $1/\sqrt{(n)}$ . All other output quantities will be correct.

**NE\_G13AS\_DIAG**

This is an unlikely exit. At least one of the diagonal elements of **rc** was found to be either negative or zero. In this case all off-diagonal elements of **rc** are returned as zero and all diagonal elements of **rc** set to  $1/\sqrt{(n)}$ .

**NE\_ALLOC\_FAIL**

Memory allocation failed.

**NE\_INTERNAL\_ERROR**

An internal error has occurred in this function. Check the function call and any array sizes. If the call is correct then please consult NAG for assistance.

## 6 Further Comments

### 6.1 Accuracy

The computations are believed to be stable.

### 6.2 References

Box G E P and Ljung G M (1978) On a measure of lack of fit in time series models *Biometrika* **65** 297–303

McLeod A I (1978) On the distribution of the residual autocorrelations in Box–Jenkins models *J. Roy. Statist. Soc. Ser. B* **40** 296–302

### 6.3 Timing

The time taken by the routine depends upon the number of residual autocorrelations to be computed,  $m$ .

### 6.4 Choice of $m$

The number of residual autocorrelations to be computed,  $m$  should be chosen to ensure that when the ARMA model (1) is written as either an infinite order autoregressive process:

$$W_t - \mu = \sum_{j=1}^{\infty} \pi_j (W_{t-j} - \mu) + \epsilon_t$$

or as an infinite order moving average process:

$$W_t - \mu = \sum_{j=1}^{\infty} \psi_j \epsilon_{t-j} + \epsilon_t$$

then the two sequences  $\{\pi_1, \pi_2, \dots\}$  and  $\{\psi_1, \psi_2, \dots\}$  are such that  $\pi_j$  and  $\psi_j$  are approximately zero for  $j > m$ . An over-estimate of  $m$  is therefore preferable to an under-estimate of  $m$ . In many instances the choice  $m = 10$  will suffice. In practice, to be on the safe side, the user should try setting  $m = 20$ .

### 6.5 Approximate Standard Errors

When **fail.code** is returned as **NE\_G13AS\_FACT** or **NE\_G13AS\_DIAG** all the standard errors in **rc** are set to  $1/\sqrt{n}$ . This is the asymptotic standard error of  $\hat{r}_l$  when all the autoregressive and moving average parameters are assumed to be known rather than estimated.

## 7 See Also

None.

## 8 Example

A program to fit an ARIMA(1,1,2) model to a series of 30 observations. 10 residual autocorrelations are computed.

### 8.1 Program Text

```
/* nag_tsa_resid_corr (g13asc) Example Program.
 *
 * Copyright 2000 Numerical Algorithms Group.
 *
 * Mark 6, 2000.
 */

#include <stdio.h>
#include <nag.h>
#include <nag_stdlib.h>
#include <nagg13.h>
#include <nagx04.h>

int main (void)
{
    double chi, df, objf, *par=0, *r=0, *rc=0, *res, s, *sd=0, siglev;
    double *x=0;
    Integer i, idf, m, *mr=0, narma, npar, nres;
    Integer nx, nseries;
    Integer exit_status=0;
```

```

Nag_ArimaOrder arimav;
Nag_TransfOrder transfv;
Nag_G13_Opt options;
NagError fail;

INIT_FAIL(fail);
Vprintf("g13asc Example Program Results\n\n");

/* Skip heading in data file */
Vscanf("%*[^\n]");

Vscanf("%ld%*[^\n]", &nx);
if (!(x = NAG_ALLOC(nx, double))
    || !(mr = NAG_ALLOC(7, Integer)))
{
    Vprintf("Allocation failure\n");
    exit_status = -1;
    goto END;
}

for (i = 1; i <= nx; ++i)
    Vscanf("%lf", &x[i - 1]);
Vscanf("%*[^\n]");
for (i = 1; i <= 7; ++i)
    Vscanf("%ld", &mr[i - 1]);
Vscanf("%*[^\n]");

npar = mr[0] + mr[2] + mr[3] + mr[5] + 1;
if (!(par = NAG_ALLOC(npar, double))
    || !(sd = NAG_ALLOC(npar, double)))
{
    Vprintf("Allocation failure\n");
    exit_status = -1;
    goto END;
}
for (i = 1; i <= npar; ++i)
    par[i - 1] = 0.0;

nseries = 1;
arimav.p = mr[0];
arimav.d = mr[1];
arimav.q = mr[2];
arimav.bigr = mr[3];
arimav.bigrd = mr[4];
arimav.bigrq = mr[5];
arimav.s = mr[6];
g13bxc(&options);
g13byc(nseries, &transfv, &fail);
g13bec(&arimav, nseries, &transfv, par, npar, nx, x, nseries, sd, &s, &objf,
&df, &options, &fail);
nres = options.lenres;
res = options.res;
if (fail.code != NE_NOERROR)
{
    Vprintf("Error from g13bec.\n%s\n", fail.message);
    exit_status = 1;
    goto END;
}

```

```

m = 10;
if (!(r = NAG_ALLOC(m, double))
    || !(rc = NAG_ALLOC(m*m, double)))
{
    Vprintf("Allocation failure\n");
    exit_status = -1;
    goto END;
}

narma = mr[0] + mr[2] + mr[3] + mr[5];
g13asc(&arimav, nres, res, m, par, narma, r, rc,
        m, &chi, &idf, &siglev, &fail);
if (fail.code != NE_NOERROR)
{
    Vprintf("Error from g13asc.\n%s\n", fail.message);
    exit_status = 1;
    goto END;
}
Vprintf("\nRESIDUAL AUTOCORRELATION FUNCTION\n-----\n--\n");
Vprintf("R(K)          ");
for (i=0; i<m; i++)
    Vprintf("%10.3f", r[i]);
Vprintf("\nStandard Error      ");
for (i=0; i<m; i++)
    Vprintf("%10.3f", rc[10*i+i]);
Vprintf("\n");
g13xzc(&options);

END:
if (x) NAG_FREE(x);
if (mr) NAG_FREE(mr);
if (par) NAG_FREE(par);
if (sd) NAG_FREE(sd);
if (r) NAG_FREE(r);
if (rc) NAG_FREE(rc);
return exit_status;
}

```

## 8.2 Program Data

```

g13asc Example Program Data
30           : nx, length of the time series
-217 -177 -166 -136 -110  -95  -64  -37
-14   -25  -51  -62  -73  -88  -113 -120
-83   -33  -19   21   17   44   44   78
  88   122  126  114   85   64       : End of time series
1  1  2  0  0  0  0  : mr, orders vector of the model

```

### 8.3 Program Results

g13asc Example Program Results

Parameters to g13bec

---

nseries.....	1	cfixed.....	FALSE
criteria.....	Nag_Exact	beta.....	1.00e+01
alpha.....	1.00e-02	gamma.....	1.00e-07
delta.....	1.00e+03		
print_level.....	Nag_Soln		
outfile.....	stdout		

The number of iterations carried out is 15

The final values of the parameters and their standard deviations are

i	para[i]	sd
1	-0.094096	0.361543
2	-0.579152	0.295984
3	-0.611889	0.182241
4	9.932425	7.050207

The residual sum of squares = 9.436281e+03

The objective function = 9.762154e+03

The degrees of freedom = 25.00

RESIDUAL AUTOCORRELATION FUNCTION

---

R(K)	0.030	0.026	-0.039	0.043	-0.129	-0.062	-0.218
-0.105	-0.024	-0.072					
Standard Error	0.011	0.116	0.122	0.147	0.171	0.171	0.179
0.182	0.182	0.184					

---