

## nag\_robust\_m\_estim\_1var (g07dbc)

### 1. Purpose

**nag\_robust\_m\_estim\_1var (g07dbc)** computes an  $M$ -estimate of location with (optional) simultaneous estimation of the scale using Huber's algorithm.

### 2. Specification

```
#include <nag.h>
#include <nagg07.h>

void nag_robust_m_estim_1var(Nag_SigmaSimulEst sigma_est, Integer n,
                             double x[], Nag_PsiFun psifun, double c, double h1,
                             double h2, double h3, double dchi, double *theta,
                             double *sigma, Integer maxit, double tol, double rs[],
                             Integer *nit, double sorted_x[], NagError *fail)
```

### 3. Description

The data consists of a sample of size  $n$ , denoted by  $x_1, x_2, \dots, x_n$ , drawn from a random variable  $X$ .

The  $x_i$  are assumed to be independent with an unknown distribution function of the form

$$F((x_i - \theta)/\sigma)$$

where  $\theta$  is a location parameter, and  $\sigma$  is a scale parameter.  $M$ -estimators of  $\theta$  and  $\sigma$  are given by the solution to the following system of equations:

$$\sum_{i=1}^n \psi \left( \left( x_i - \hat{\theta} \right) / \hat{\sigma} \right) = 0 \quad (1)$$

$$\sum_{i=1}^n \chi \left( \left( x_i - \hat{\theta} \right) / \hat{\sigma} \right) = (n - 1)\beta \quad (2)$$

where  $\psi$  and  $\chi$  are given functions, and  $\beta$  is a constant, such that  $\hat{\sigma}$  is an unbiased estimator when  $x_i$ , for  $i = 1, 2, \dots, n$  has a normal distribution. Optionally, the second equation can be omitted and the first equation is solved for  $\hat{\theta}$  using an assigned value of  $\sigma = \sigma_c$ .

The values of  $\psi \left( \frac{x_i - \hat{\theta}}{\hat{\sigma}} \right) \hat{\sigma}$  are known as the Winsorized residuals.

The following functions are available for  $\psi$  and  $\chi$  in nag\_robust\_m\_estim\_1var;

#### (a) Null Weights

$$\psi(t) = t \quad \chi(t) = \frac{t^2}{2}$$

Use of these null functions leads to the mean and standard deviation of the data.

#### (b) Huber's Function

$$\begin{aligned} \psi(t) &= \max(-c, \min(c, t)) & \chi(t) &= \frac{|t|^2}{2} |t| \leq d \\ & & \chi(t) &= \frac{d^2}{2} |t| > d \end{aligned}$$

## (c) Hampel's Piecewise Linear Function

$$\begin{aligned}
 \psi_{h_1, h_2, h_3}(t) &= -\psi_{h_1, h_2, h_3}(-t) \\
 &= t & 0 \leq t \leq h_1 & \chi(t) = \frac{|t|^2}{2} |t| \leq d \\
 &= h_1 & h_1 \leq t \leq h_2 \\
 &= h_1(h_3 - t)/(h_3 - h_2) & h_2 \leq t \leq h_3 & \chi(t) = \frac{d^2}{2} |t| > d \\
 &= 0 & t > h_3
 \end{aligned}$$

## (d) Andrew's Sine Wave Function

$$\begin{aligned}
 \psi(t) &= \sin t & -\pi \leq t \leq \pi & \chi(t) = \frac{|t|^2}{2} |t| \leq d \\
 &= 0 & \text{otherwise} & \chi(t) = \frac{d^2}{2} |t| > d
 \end{aligned}$$

## (e) Tukey's Bi-weight

$$\begin{aligned}
 \psi(t) &= t(1 - t^2)^2 & |t| \leq 1 & \chi(t) = \frac{|t|^2}{2} |t| \leq d \\
 &= 0 & \text{otherwise} & \chi(t) = \frac{d^2}{2} |t| > d
 \end{aligned}$$

where  $c$ ,  $h_1$ ,  $h_2$ ,  $h_3$  and  $d$  are constants.

Equations (1) and (2) are solved by a simple iterative procedure suggested by Huber:

$$\hat{\sigma}_k = \sqrt{\frac{1}{\beta(n-1)} \left( \sum_{i=1}^n \chi \left( \frac{x_i - \hat{\theta}_{k-1}}{\hat{\sigma}_{k-1}} \right) \right) \hat{\sigma}_{k-1}^2}$$

and

$$\hat{\theta}_k = \hat{\theta}_{k-1} + \frac{1}{n} \sum_{i=1}^n \psi \left( \frac{x_i - \hat{\theta}_{k-1}}{\hat{\sigma}_k} \right) \hat{\sigma}_k$$

or

$$\hat{\sigma}_k = \sigma_c, \quad \text{if } \sigma \text{ is fixed.}$$

The initial values for  $\hat{\theta}$  and  $\hat{\sigma}$  may either be user-supplied or calculated within nag\_robust\_m\_estim\_1var as the sample median and an estimate of  $\sigma$  based on the median absolute deviation respectively.

nag\_robust\_m\_estim\_1var is based upon subroutine LYHALG within the ROBETH library, see Marazzi (1987).

**4. Parameters****sigma.est**

Input: the value assigned to **sigma.est** determines whether  $\hat{\sigma}$  is to be simultaneously estimated.

**sigma.est = Nag\_SigmaBypas**

The estimation of  $\hat{\sigma}$  is bypassed and **sigma** is set equal to  $\sigma_c$ ;

**sigma.est = Nag\_SigmaSimul**

$\hat{\sigma}$  is estimated simultaneously.

**n**

Input: the number of observations,  $n$ .

Constraint: **n** > 1.

**x[n]**

Input: the vector of observations,  $x_1, x_2, \dots, x_n$ .

**psifun**

Input: which  $\psi$  function is to be used.

**psifun = Nag\_Lsq,**

$$\psi(t) = t$$

**psifun = Nag\_HuberFun,**

Huber's function,

**psifun = Nag\_HampelFun,**

Hampel's piecewise linear function,

**psifun = Nag\_AndrewFun,**

Andrew's sine wave,

**psifun = Nag\_TukeyFun,**

Tukey's bi-weight.

Constraint: **psifun = Nag\_Lsq, Nag\_HuberFun, Nag\_HampelFun, Nag\_AndrewFun or Nag\_TukeyFun.**

**c**

If **psifun = Nag\_HuberFun** on entry, **c** must specify the parameter,  $c$ , of Huber's  $\psi$  function.

**c** is not referenced if **psifun ≠ Nag\_HuberFun**.

Constraint: **c > 0.0** if **psifun = Nag\_HuberFun**.

**h1****h2****h3**

If **psifun = Nag\_HampelFun** on entry, **h1**, **h2**, and **h3** must specify the parameters  $h_1$ ,  $h_2$ , and  $h_3$ , of Hampel's piecewise linear  $\psi$  function. **h1**, **h2**, and **h3** are not referenced if **psifun ≠ Nag\_HampelFun**.

Constraint:  $0 \leq h1 \leq h2 \leq h3$  and  $h3 > 0.0$  if **psifun = Nag\_HampelFun**.

**dchi**

Input: the parameter,  $d$ , of the  $\chi$  function. **dchi** is not referenced if **psifun = Nag\_Lsq**.

Constraint: **dchi > 0.0** if **psifun ≠ Nag\_Lsq**.

**theta**

Input: if **sigma > 0** then **theta** must be set to the required starting value of the estimation of the location parameter  $\hat{\theta}$ . A reasonable initial value for  $\hat{\theta}$  will often be the sample mean or median.

Output: the  $M$ -estimate of the location parameter,  $\hat{\theta}$ .

**sigma**

The role of **sigma** depends on the value assigned to **sigma.est** (see above) as follows:

**sigma.est = Nag\_SigmaSimul**

Input: **sigma** must be assigned a value which determines the values of the starting points for the calculations of  $\hat{\theta}$  and  $\hat{\sigma}$ . If **sigma ≤ 0.0** then **nag\_robust\_m\_estim\_1var** will determine the starting points of  $\hat{\theta}$  and  $\hat{\sigma}$ . Otherwise the value assigned to **sigma** will be taken as the starting point for  $\hat{\sigma}$ , and **theta** must be assigned a value before entry, see above.

**sigma.est = Nag\_SigmaBypas**

Input: **sigma** must be assigned a value which determines the value of  $\sigma_c$ , which is held fixed during the iterations, and the starting value for the calculation of  $\hat{\theta}$ . If **sigma ≤ 0**, then **nag\_robust\_m\_estim\_1var** will determine the value of  $\sigma_c$  as the median absolute deviation adjusted to reduce bias and the starting point for  $\hat{\theta}$ . Otherwise, the value assigned to **sigma** will be taken as the value of  $\sigma_c$  and **theta** must be assigned a relevant value before entry, see above.

Output: **sigma** contains the  $M$ -estimate of the scale parameter,  $\hat{\sigma}$ , if **sigma.est** was assigned the value **Nag\_SigmaSimul** on entry, otherwise **sigma** will contain the initial fixed value  $\sigma_c$ .

**maxit**

Input: the maximum number of iterations that should be used during the estimation.  
 Suggested value: **maxit** = 50.  
 Constraint: **maxit** > 0.

**tol**

Input: the relative precision for the final estimates. Convergence is assumed when the increments for **theta**, and **sigma** are less than **tol** × max(1.0,  $\sigma_{k-1}$ ).  
 Constraint: **tol** > 0.0.

**rs[n]**

Output: the Winsorized residuals.

**nit**

Output: the number of iterations that were used during the estimation.

**sorted\_x[n]**

Output: if **sigma** ≤ 0.0 on entry, **sorted\_x** will contain the  $n$  observations in ascending order.

**fail**

The NAG error parameter, see the Essential Introduction to the NAG C Library.

## 5. Error Indications and Warnings

**NE\_INT\_ARG\_LT**

On entry, **n** must not be less than or equal to 1: **n** = ⟨value⟩.  
 On entry, **maxit** must not be less than or equal to 0: **maxit** = ⟨value⟩.

**NE\_REAL\_ARG\_LE**

On entry, **tol** must not be less than or equal to 0.0: **tol** = ⟨value⟩.

**NE\_BAD\_PARAM**

On entry, parameter **sigma\_est** had an illegal value.  
 On entry, parameter **psifun** had an illegal value.

**NE\_REAL\_ENUM\_ARG\_CONS**

On entry, **c** = ⟨value⟩, **psifun** = ⟨value⟩.  
 These parameters must satisfy **c**>0, **psifun**=**Nag\_HuberFun**.  
 On entry, **h1** = ⟨value⟩, **psifun** = ⟨value⟩.  
 These parameters must satisfy **h1** ≥ 0, **psifun**=**Nag\_HampelFun**.  
 On entry, **dchi** = ⟨value⟩, **psifun** = ⟨value⟩.  
 These parameters must satisfy **dchi**>0, **psifun** ≠ **Nag\_Lsq**.

**NE\_2\_REAL\_ENUM\_ARG\_CONS**

On entry, **h1** = ⟨value⟩, **h2** = ⟨value⟩ and **psifun** = ⟨value⟩.  
 These parameters must satisfy **h1** ≤ **h2**, **psifun**=**Nag\_HampelFun**.  
 On entry, **h1** = ⟨value⟩, **h3** = ⟨value⟩ and **psifun** = ⟨value⟩.  
 These parameters must satisfy **h1** ≤ **h3**, **psifun**=**Nag\_HampelFun**.  
 On entry, **h2** = ⟨value⟩, **h3** = ⟨value⟩ and **psifun** = ⟨value⟩.  
 These parameters must satisfy **h2** ≤ **h3**, **psifun**=**Nag\_HampelFun**.

**NE\_3\_REAL\_ENUM\_ARG\_CONS**

On entry, **h1** = ⟨value⟩, **h2** = ⟨value⟩, **h3** = ⟨value⟩, **psifun** = ⟨value⟩.  
 These parameters must satisfy **h1=h2=h3** ≠ 0.0, **psifun**=**Nag\_HampelFun**.

**NE\_ALL\_ELEMENTS\_EQUAL**

On entry, all the values in the array **x** must not be equal.

**NE\_ESTIM\_SIGMA\_ZERO**

The estimated value of **sigma** was ≤ 0.0 during an iteration.

**NE\_TOO\_MANY**

Too many iterations (⟨value⟩).

**NE\_WINS\_RES\_ZERO**

The Winsorized residuals are zero.

On completion of the iterations, the Winsorized residuals were all zero. This may occur when using the **sigma\_est = Nag\_SigmaBypas** option with a redescending  $\psi$  function, i.e., Hampel's piecewise linear function, Andrew's sine wave, and Tukey's biweight.

If the given value of  $\sigma$  is too small, then the standardised residuals  $\frac{x_i - \hat{\theta}_k}{\sigma_c}$ , will be large and all the residuals may fall into the region for which  $\psi(t) = 0$ . This may incorrectly terminate the iterations thus making **theta** and **sigma** invalid.

Re-enter the routine with a larger value of  $\sigma_c$  or with **sigma\_est = Nag\_SigmaSimul**.

**NE\_INTERNAL\_ERROR**

An internal error has occurred in this function. Check the function call and any array sizes. If the call is correct then please consult NAG for assistance.

**6. Further Comments**

When the user supplies the initial values, care has to be taken over the choice of the initial value of  $\sigma$ . If too small a value of  $\sigma$  is chosen then initial values of the standardized residuals  $\frac{x_i - \hat{\theta}_k}{\sigma}$  will be large. If the redescending  $\psi$  functions are used, i.e., Hampel's piecewise linear function, Andrew's sine wave, or Tukey's bi-weight, then these large values of the standardised residuals are Winsorized as zero. If a sufficient number of the residuals fall into this category then a false solution may be returned, see Hampel (1986) page 152.

**6.1. Accuracy**

On successful exit the accuracy of the results is related to the value of TOL, see Section 4.

**6.2. References**

- Hampel F R, Ronchetti E M, Rousseeuw P J and Stahel W A (1986) *Robust statistics. The approach based on influence functions*. Wiley  
 Huber P J (1981) *Robust statistics*. Wiley  
 Marazzi A (1987) Subroutines for Robust Estimation of Location and Scale in ROBETH *Cah Rech Doc IUMSP, No. 3 ROB 1*. Institut Universitaire de Médecine Sociale et Préventive, Lausanne

**7. See Also**

None.

**8. Example**

The following program reads in a set of data consisting of eleven observations of a variable  $X$ .

For this example, Hampel's Piecewise Linear Function is used (**psifun = Nag\_HampelFun**), values for  $h_1$ ,  $h_2$  and  $h_3$  along with  $d$  for the  $\chi$  function, being read from the data file.

Using the following starting values various estimates of  $\theta$  and  $\sigma$  are calculated and printed along with the number of iterations used:

- (a) nag\_robust\_m\_estim\_1var determines the starting values,  $\sigma$  is estimated simultaneously.
- (b) The user supplies the starting values,  $\sigma$  is estimated simultaneously.
- (c) nag\_robust\_m\_estim\_1var determines the starting values,  $\sigma$  is fixed.
- (d) The user supplies the starting values,  $\sigma$  is fixed.

### 8.1. Program Text

```

/* nag_robust_m_estim_1var(g07dbc) Example Program.
*
* Copyright 1996 Numerical Algorithms Group.
*
* Mark 4, 1996.
*/
#include <nag.h>
#include <nag_stdlib.h>
#include <nag_string.h>
#include <stdio.h>
#include <nagg07.h>

#define NMAX 25

main()
{
    double dchi;
    double c;
    double x[NMAX], sigma, theta;
    double h1, h2, h3, rs[NMAX];
    double thesav, sigsav;
    double tol, wrk[NMAX];

    Integer ipsi;
    Integer i;
    Integer n;
    Integer maxit;
    Integer isigma;
    Integer nit;

    char sigma_enum_str[20];

    Nag_SigmaSimulEst sigma_enum;

    Vprintf("g07dbc Example Program Results\n\n");

    /* Skip heading in data file */
    Vscanf("%*[^\n]\n");

    Vscanf("%ld %*[^\n]\n", &n);
    if (n <= NMAX)
    {
        for (i = 1; i <= n; ++i)
            Vscanf("%lf", &x[i - 1]);
        Vscanf("%*[^\n]\n");
        Vscanf("%lf %lf %lf %lf %d %*[^\n]\n", &h1, &h2, &h3, &dchi, &maxit);
        Vprintf("%25sInput parameters      Output parameters\n","");
        Vprintf("      sigma_est      sigma      theta      tol      sigma      theta\n\n");
        while ((scanf("%lf %lf %lf %lf%*[^\n]", &isigma, &sigma, &theta, &tol)) != EOF)
        {
            if (isigma == 1)
            {
                sigma_enum = Nag_SigmaSimul;
                strcpy(sigma_enum_str, "Nag_SigmaSimul");
            }
            else if (isigma == 0)
            {
                sigma_enum = Nag_SigmaBypas;
                strcpy(sigma_enum_str, "Nag_SigmaBypas");
            }
            sigsav = sigma;
            thesav = theta;
            c = 0.0;

            g07dbc(sigma_enum, n, x, Nag_HampelFun, c, h1, h2, h3, dchi, &theta,
                    &sigma, maxit, tol, rs, &nit, wrk, NAGERR_DEFAULT);
    }
}

```

```

        Vprintf("%s      %8.4f %8.4f %7.4f %9.4f %8.4f\n", sigma_enum_str,
                 sigsav, thesav,tol,sigma,theta);
    }
    exit(EXIT_SUCCESS);
}
else
{
    Vprintf("n is out of range: n =%ld\n", n);
    exit(EXIT_SUCCESS);
}
}

```

## 8.2. Program Data

```

g07dbc Example Program Data
11                      : Number of observations
13.0 11.0 16.0 5.0 3.0 18.0 9.0 8.0 6.0 27.0 7.0 : Observations
1.5 3.0 4.5 1.5 50   : h1   h2   h3   dchi  maxit
1     -1.0   0.0   0.0001 :isigma  sigma  theta  tol
1      7.0    2.0   0.0001
0     -1.0   0.0   0.0001
0      7.0    2.0   0.0001

```

## 8.3. Program Results

g07dbc Example Program Results

sigma_est	Input parameters			Output parameters	
	sigma	theta	tol	sigma	theta
Nag_SigmaSimul	-1.0000	0.0000	0.0001	6.3247	10.5487
Nag_SigmaSimul	7.0000	2.0000	0.0001	6.3249	10.5487
Nag_SigmaBypas	-1.0000	0.0000	0.0001	5.9304	10.4896
Nag_SigmaBypas	7.0000	2.0000	0.0001	7.0000	10.6500

---